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Computer algebra solution to Mie scattering problem for the stratified sphere with nonlocal plasmonic layers Ivan Lopushenko

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 ∂D_1

 D_2

is considered.

 D_0

Fig. 1. Geometry of the model: plane

wave scattering on the sphere with

transparent core (refractive index 1.4,

 $r_1 = 3nm$) and silver shell ($r_2 = 6nm$)

Abstract

- Scattering by spherical particle with an arbitrary amount of concentric layers optionally featuring spatial dispersion effects is considered;
- Several problem statements featuring different boundary condition sets are examined with a coreshell particle as an example; • Computer algebra code (symMie) based on the MATLAB/Octave symbolic engine is implemented to solve the problem for the **user-defined boundary** condition set.

Motivation

Plasmonic particles with scale less than 10 nm are known to exhibit unique scattering properties related to the quantum spatial dispersion effects [1-3]. These are not accounted for in the majority of electromagnetic solvers that are conventionally used to simulate scattering. Rigorous evaluation of such structures via i.e. Time-Dependent Density Functional Theory (TDDFT) is possible but computationally demanding for large particles (d > 5nm) [4]. Due to the widespread of these particles in cutting-edge applications [5], several nonlocal-corrected Maxwell-based models were recently proposed in attempt to interpret dispersive phenomena in terms of classic constitutive equations and boundary conditions (BC). Each model, i.e. Mie theory in local response approximation (LRA), Drude hydrodynamic theory (HDT), Generalized Nonlocal Optical Response (GNOR), or approach based on mesoscopic Feibelman formalism implies its own scattering problem statement involving possibly modified Maxwell equations and BC [1-3,6-8]. Aim of the current work is to demonstrate the advantages of a computer algebra approach capable of solving scattering by spherical layered particle for the user-defined BC set employing complete $\mathbf{M}_{e_{mn}}$, $\mathbf{N}_{e_{mn}}$, $\mathbf{L}_{e_{mn}}$ functional basis.

Local response approximation (LRA)

We consider glass core (D_0) and Ag shell (D_1) sphere in free space (D_2) as an example.

 $\operatorname{curl} \mathbf{H}_{\zeta}(M) = -jk\varepsilon_{\zeta}\mathbf{E}_{\zeta}(M),$ $M \in D_{\zeta}$, $\operatorname{curl} \mathbf{E}_{\zeta}(M) = jk\mu_{\zeta}\mathbf{H}_{\zeta}(M),$ (1) $\zeta = 0, 1, 2,$ $\operatorname{div}\mathbf{E}_{\zeta}(M)=0,$ $\operatorname{div}\mathbf{H}_{\zeta}(M)=0,$ $P\in\partial D_{\zeta+1'}$ $|\mathbf{E}_{\zeta}(P) \times \mathbf{n}_{P}| = |\mathbf{E}_{\zeta+1}(P) \times \mathbf{n}_{P}|,$ $|\mathbf{H}_{\zeta}(P) \times \mathbf{n}_{P}| = |\mathbf{H}_{\zeta+1}(P) \times \mathbf{n}_{P}|.$

Maxwell equations and boundary conditions are the same for all layers allowing direct analytic and numeric solutions for an arbitrary amount of layers.

Spatial dispersion (HDT/GNOR) Ag shell D_2 is now nonlocal, particle is the same. $\operatorname{curl} \mathbf{H}_{2}(M) = -jk \left(\varepsilon_{2} + \frac{\beta_{2}^{2} \left(\varepsilon_{2}' + d_{2}(\gamma_{2} + j\omega) \right)}{\omega(\omega + j\gamma_{2})} \operatorname{graddiv} \right) \mathbf{E}_{2}(M),$ $\operatorname{curl} \mathbf{H}_1(M) = -jk\varepsilon_1 \mathbf{E}_1(M),$ $M \in D_{\mathcal{Z}}$,

Solution: Mie theory with longitudinal harmonics

 $\mathbf{M}_{e_{mn}} = \operatorname{curl}(\mathbf{r}\psi_{e_{mn}}),$ $\psi_{\substack{e\\o}mn}^{(i)} = z_n^{(i)} (k_{\zeta} r) P_n^m (\cos\theta) \begin{cases} \cos m\varphi \\ \sin m\varphi \end{cases}$ Complete set of the spherical $\partial D_2 \quad \mathbf{N}_{emn}^e = \operatorname{curl}(\mathbf{M}_{emn}^e)/k_{\zeta}, \quad \text{vector wave functions (SVWFs)}$ $z_n^{(i)}(kr) = \left[j_n(kr), y_n(kr), h_n^{(1)}(kr), h_n^{(2)}(kr) \right]$ $\mathbf{L}_{omn}^{e} = \operatorname{grad}(\mathbf{r}\psi_{omn}^{e}),$ Incident field: $\mathbf{E}_{i} = E_{0} \sum_{n=1}^{\infty} j^{n} \frac{2n+1}{n(n+1)} \left(\mathbf{M}_{o1n}^{(1)} - j \mathbf{N}_{e1n}^{(1)} \right), \mathbf{H}_{i} = \frac{-k_{2}}{\omega \mu_{2}} E_{0} \sum_{n=1}^{\infty} j^{n} \frac{2n+1}{n(n+1)} \left(\mathbf{M}_{e1n}^{(1)} + j \mathbf{N}_{o1n}^{(1)} \right), (3a)$ Scattered field: $\mathbf{E}_{s} = \sum_{n=1}^{\infty} E_{n} \left(j a_{n} \mathbf{N}_{e1n}^{(3)} - b_{n} \mathbf{M}_{o1n}^{(3)} \right), \ \mathbf{H}_{s} = \frac{k_{2}}{\omega \mu_{2}} \sum_{n=1}^{\infty} E_{n} \left(j b_{n} \mathbf{N}_{o1n}^{(3)} + a_{n} \mathbf{M}_{e1n}^{(3)} \right),$ (3b)Local core: $\mathbf{E}_0 = \mathbf{E}_0^T = \sum_{n=1}^{\infty} E_n \left(c_n \mathbf{M}_{o1n}^{(1)} - j d_n \mathbf{N}_{e1n}^{(1)} \right), \ \mathbf{H}_0 = \frac{-k_0}{\omega \mu_0} \sum_{n=1}^{\infty} E_n \left(d_n \mathbf{M}_{e1n}^{(1)} + j c_n \mathbf{N}_{o1n}^{(1)} \right),$ (3c)Nonlocal core: $\mathbf{E}_0 = \mathbf{E}_0^T |_{k_0^T} + \mathbf{E}_0^L |_{k_0^L}$, $\mathbf{E}_0^L = -j \sum_{n=1}^{\infty} f_n \mathbf{L}_{e1n}^{(1)}$, \mathbf{H}_0 does not change (curl $\mathbf{E}_{\zeta}^L = 0$), (3d) Local shell: $\mathbf{E}_1 = \mathbf{E}_1^T = \sum_{n=1}^{\infty} \left(A_n \mathbf{M}_{o1n}^{(1)} - j B_n \mathbf{N}_{e1n}^{(1)} + \Gamma_n \mathbf{M}_{o1n}^{(2)} - j K_n \mathbf{N}_{e1n}^{(2)} \right), \ \mathbf{H}_1 = \frac{-k_1}{\omega u_1} \operatorname{curl}(\mathbf{E}_1),$ (3e) Nonlocal shell: $\mathbf{E}_1 = \mathbf{E}_1^T \Big|_{k_1^T} + \mathbf{E}_1^L \Big|_{k_1^L}$, $\mathbf{E}_1^L = -j \sum_{n=1}^{\infty} (h_n \mathbf{L}_{e1n}^{(1)} + q_n \mathbf{L}_{e1n}^{(2)})$, \mathbf{H}_1 does not change. (3f)

Computer algebra implementation & results

Within symMie, SVWF set is implemented into symbolic MATLAB/Octave functions, along with $\{E_{\zeta}, H_{\zeta}\}$ expansions (3). Expansion coefficients $a_n, b_n, \dots, h_n, q_n$ are then evaluated symbolically using boundary conditions defined by the user. Some examples of the BC input data are provided below along with the simulation results. It is assumed that

$\operatorname{curl} \mathbf{E}_{\zeta}(M) = jk\mu_{\zeta}\mathbf{H}_{\zeta}(M),$	
$\operatorname{div}\mathbf{E}_{\zeta}(M)=0,$	$\zeta = 0, 1, 2,$
$\operatorname{div}\mathbf{H}_{\zeta}(M)=0,$	(2)
$[\mathbf{E}_{\zeta}(P) \times \mathbf{n}_{P}] = [\mathbf{E}_{\zeta+1}(P) \times \mathbf{n}_{P}],$	$P \in \partial D_{\zeta+1}, (2)$
$[\mathbf{H}_{\zeta}(P) \times \mathbf{n}_{P}] = [\mathbf{H}_{\zeta+1}(P) \times \mathbf{n}_{P}].$,
$\varepsilon_1' \mathbf{E}_1(P) \cdot \mathbf{n}_P = \varepsilon_2 \mathbf{E}_2(P) \cdot \mathbf{n}_P,$	$P\in\partial D_2,$
$\varepsilon_1' \mathbf{E}_1(P) \cdot \mathbf{n}_P = \varepsilon_0 \mathbf{E}_0(P) \cdot \mathbf{n}_P,$	$P\in\partial D_1.$

Maxwell equation within Ag layer is modified and additional boundary conditions are imposed on both metal-dielectric surface boundaries [1,2]. Moreover, for metal-metal surfaces another form of BC has to be used [1,7,8]. Hence **each configuration** of the stratified sphere can have a **unique problem statement** making it difficult to derive an analytic solution in general form.

Cornerstones of the HDT/GNOR

• Instead of the $J(M) = \sigma E(M)$ another constitutive relation is used within metal layer (D_1) [2,6,7]:

 $\left(\frac{\beta^2}{\omega(\omega+j\gamma)} + \frac{d}{j\omega}\right) \nabla [\nabla \cdot \mathbf{J}(M)] + \mathbf{J}(M) = \sigma_{\mathrm{D}}(\omega) \mathbf{E}(M);$

- This leads to the presence of the **longitudinal field** $\operatorname{curl}(\mathbf{E}_{7}^{L}) = 0$ in the metal layer along with the transversal field div $(\mathbf{E}_{\zeta}^{T}) = 0, k^{L}/k^{T} \sim 10 \div 100!$
- γ is Drude damping; $\beta^2 = 3/5v_F^2$, v_F Fermi velocity; d – electron diffusion coeff. (GNOR only); • $\varepsilon' = \varepsilon + \omega_p^2 / (\omega^2 + j\gamma\omega), \omega_p$ – metal plasma freq; "Hard-wall" boundary condition is imposed.

 $\mathbf{E}_{\zeta} = \mathbf{E}_{\zeta}(R,\theta,\varphi), \mathbf{H}_{\zeta} = \mathbf{H}_{\zeta}(R,\theta,\varphi),$ with spherical coordinates (R,θ,φ) , origin at the sphere center, $a = r_1$ and $b = r_2$.

 nm^2

ctions,

Crc

 10^{-}

300

320

Local response approximation (LRA)

BC = [subs(Eint(2),symVars.r,a) == subs(Eshl(2),symVars.r,a), ... subs(Hint(2), symVars.r,a) == subs(Hshl(2), symVars.r,a), ... subs(Eint(3),symVars.r,a) == subs(Eshl(3),symVars.r,a), ... subs(Hint(3),symVars.r,a) == subs(Hshl(3),symVars.r,a), ... subs(Eshl(2),symVars.r,b) == subs(Einc(2) + Esca(2),symVars.r,b), ... subs(Hshl(2),symVars.r,b) == subs(Hinc(2) + Hsca(2),symVars.r,b), ... subs(Eshl(3),symVars.r,b) == subs(Einc(3) + Esca(3),symVars.r,b), ... epsi.*subs(Eint(1),symVars.r,a) subs(Hshl(3),symVars.r,b) == subs(Hinc(3) + Hsca(3),symVars.r,b)];



Fig. 1. Example of the boundary conditions input data for LRA problem (1) and corresponding solution ($\sigma_{ext}, \sigma_{sca}$).

Comment: Evaluation of the expansion coefficients can be

BC = [subs(Eint(2),symVars.r,a) s(2),symVars.r,a), ... == subs(Eshl(2) + Enle(2) + 1 subs(Hint(2), symVars.r,a) == subs(Hshl(2) ,symVars.r,a), ... == subs(Eshl(3) + Enle(3) + Enls(3), symVars.r,a), ... subs(Eint(3), symVars.r,a) subs(Hint(3), symVars.r,a) == subs(Hshl(3) ,symVars.r,a), ... subs(Eshl(2) + Enle(2) + Enls(2), symVars.r,b) == subs(Einc(2) + Esca(2) ,symVars.r,b), ... ,symVars.r,b), ... subs(Hshl(2),symVars.r,b) == subs(Hinc(2) + Hsca(2) subs(Eshl(3) + Enle(3) + Enls(3), symVars.r,b) == subs(Einc(3) + Esca(3) ,symVars.r,b), ... subs(Hshl(3),symVars.r,b) == subs(Hinc(3) + Hsca(3) ,symVars.r,b), ...

Drude hydrodynamic theory (HDT)



 $-\sigma_{ext}$ (symMie)

 $-\sigma_{sca}$ (symMie)

 σ_{sca} (Ref. [8])

400

380



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BC = [ Eint(2) + Enle(2) == Einc(2) + Esca(2), ...
       Hint(2)
                         == Hinc(2) + Hsca(2), ...
       Eint(3)
                         == Einc(3) + Esca(3), ...
                         == Hinc(3) + Hsca(3), ...
      Hint(3)
epsL.*(Eint(1) + Enle(1)) == (Einc(1) + Esca(1)).*eps0]
```



Fig. 2. Example of the boundary conditions input data for HDT problem (2) and corresponding solution ($\sigma_{ext}, \sigma_{sca}$).

360

 λ , nm

Fig. 3. Example of the boundary conditions input data for scattering by homogeneous silver sphere and demonstration of the GNOR solution convergence to the LRA solution for large particles. Symbols indicate reference data [3].

(a) fully symbolic (result: all coefficients are expressed as functions of the input parameters, i.e. $a_n = a_n(r_1, r_2, \lambda, \varepsilon_0, \varepsilon_1, \varepsilon_1^T, \varepsilon_2, \dots)$; (b) partially symbolic (some input parameters are defined numerically, i.e. $r_1 = 3nm$; (c) MATLAB VPA – variable precision arithmetic (both input and output data are numeric). This enables additional flexibility in i.e. rounding error analysis. This feature appears to be important due to the presence of rapidly oscillating longitudinal fields ($k^L \gg k^T$) leading to computational issues in thin plasmonic layers [3,8].

340

Longitudinal wavenumber: $(k^L)^2 = \frac{\omega^2 + j\gamma\omega - \omega_p^2/\varepsilon'}{\beta^2 + d(\gamma + j\omega)}$, transversal wavenumber: $(k^T)^2 = k^2 \varepsilon \mu$, $\sigma_{sca} = \frac{2\pi}{k^2} \sum_{n=1}^{\infty} (2n+1)(|a_n|^2 + |b_n|^2)$, $\sigma_{ext} = \frac{2\pi}{k^2} \sum_{n=1}^{\infty} (2n+1)\operatorname{Re}(a_n + b_n)$. Conclusion

Notations

- We consider plane wave $\{\mathbf{E}_i, \mathbf{H}_i\}$ scattering;
- { \mathbf{E}_s , \mathbf{H}_s } is the scattered field in D_2 ;
- $\mathbf{E}_2 = \mathbf{E}_i + \mathbf{E}_s$, $\mathbf{H}_2 = \mathbf{H}_i + \mathbf{H}_s$ is the total field in D_2 ;
- $\{\mathbf{E}_{\zeta}, \mathbf{H}_{\zeta}\}$ are total fields in D_{ζ} layer;
- Within nonlocal layer $\mathbf{E}_{\zeta} = \mathbf{E}_{\zeta}^{T} + \mathbf{E}_{\zeta}^{L}$;
- \mathbf{n}_P is a unit outward normal to the surface at point *P*;
- $k = 2\pi/\lambda$ is a wavenumber in vacuum, $\omega = kc$;
- ε_{ζ} is experimentally measured complex permittivity;
- μ_{ζ} is permeability; $\operatorname{Im}(\varepsilon_2) = 0$, $\operatorname{Im}(\varepsilon_{\zeta}) \ge 0$.
- Radiation condition at infinity (D_2) is also imposed.

- Implemented symbolic framework allows to accurately obtain **both analytic and numeric** solutions for the stratified sphere with nonlocal layers. Boundary conditions can be flexibly defined by user via built-in field expansions.
- Applications of the proposed symMie tool include, but are not limited to: (a) versatile comparison of the different physical approaches to the e/m scattering problem; (b) ground for verification of pure numerical high-performance techniques; (c) estimation of the solution to scattering problem without the need to implement any problem-specific code.
- This framework can potentially be expanded to the broader scope of boundary-value problems from any field of mathematical physics given that it allows analytic solution in terms of expansion to the complete basis function series.

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